

**IN THE SPECIFICATION:**

The specification as amended below with a replacement paragraphs shows added text with underlining and deleted text with ~~striketrough~~.

Please REPLACE the paragraph beginning at page 15, line 10, with the following paragraph:

According to the present invention, as described above, the workpiece gripped state established by the hand can be observed without-a stopping the robot. This prevents the tact time from being affected. Furthermore, a flexible and inexpensive system can be constructed which need not use any exclusive conveyors even for large-sized workpieces.